One-dimensional I test and direction vector I test with array references by induction variable

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Abstract: In this paper, theoretical aspects to demonstrate the accuracy of the Interval Test (the I test and the direction vector I test) to be applied for resolving the problem stated above is presented. Also, it is proved from the proposed theoretical aspects that under a specific direction vector $\vec{\theta} = (=_1, \dots, =_d)$ there are *integer-valued* solutions for one-dimensional arrays with subscripts formed by induction variable and under other specific direction vectors there are *no* integer-valued solutions. Experiments with benchmarks, cited from Parallel loop, Vector loop and TRFD (Perfect benchmark), reveal that our framework can properly enhance the precision of data dependence analysis for one-dimensional arrays with subscripts mentioned above.

Keywords: parallelising/vectorising compilers; data dependence analysis; loop parallelisation; loop vectorisation; automatic loop transformation.

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1 INTRODUCTION

Achieving a good data dependence analysis is a critical, issue in order to reduce the communication overhead and to exploit parallelism of applications as much as possible. This task becomes even more important in distributed memory systems where, in addition to accomplishing a high parallelism of computation and low communication overhead among the processors, it is essential to develop a new analysis technique for data dependence.

well-known data are several dependence analysis algorithms applicable for *one-dimensional* arrays under constant bounds or variable bounds: the GCD test (Banerjee, 1988, 1993, 1997), Banerjee's method (Banerjee, 1988, 1993, 1997), the I test and the direction vector I test (Kong et al., 1991; Niedzielski and Psarris, 1999; Psarris et al., 1991, 1993; Psarris and Kyriakopoulos, 1999), the extended I test (Chang and Chu, 1998), the generalised direction vector I test (Chang and Chu, 2001) and the interval reduction test (Huang and Yang, 2000). There are also several well-known data dependence analysis algorithms applicable for multi-dimensional coupled arrays under constant bounds or variable bounds: the generalised GCD test (Banerjee, 1988, 1993, 1997), the Lambda test (Li et al., 1990), the generalised Lambda test (Chang et al., 1999), the multi-dimensional I test (Chang et al., 2001), the multi-dimensional direction vector I test (Chang et al., 2002), the Power test (Wolfe and Tseng, 1992) and the Omega test (Pugh, 1992). There are several well-known data dependence analysis algorithms applicable for arrays with linear subscripts with symbolic coefficients, or with non-linear subscripts under *symbolic* bounds: the infinity Banerjee test (Petersen, 1993), the Range test (Blume and Eigenmann, 1998), the infinity Lambda test (Chang and Chu, 2000), the access range test (Paek, 1997; Hoeflinger, 1998) and one analysis method for pointers and induction variables (Wu, 2001).

In this paper, we propose a sophisticated technique of data dependence analysis. This approach is to test dependence if there are *integer-valued* solutions for one-dimensional arrays with subscripts formed by induction variable. Without direction vectors, there are integer-valued solutions for one-dimensional arrays with subscripts formed by induction variable. Furthermore, it is also shown that under a specific direction vector $\vec{\theta} = (=_1, ..., =_d)$ there are integer-valued solutions for one-dimensional arrays with subscripts formed by induction variable.

Shen et al. (1992) had indicated that in real programmes one-dimensional arrays with subscripts formed by induction variable occur quite frequently. A *d*-nested loop accessing a one-dimensional array with subscripts formed by induction variable is shown in Figure 1.

$$K=0$$

$$FOR \ I_{l_1} = L_1 \ TO \ U_1$$

$$\vdots$$

$$FOR \ I_d = L_d \ TO \ U_d$$

$$K=K+z$$

$$S: \qquad A(K+C) = \cdots$$

$$S: \qquad \cdots = A(K+C)\cdots$$

$$\vdots$$

$$ENDFOR$$

$$\vdots$$

Figure 1 An example of a nested loop with induction variable

Induction variable is a one scalar integer variable, which is used in a loop, to simulate loop's index variables: it is incremented or decremented by a constant amount in each iteration. Every induction variable can be replaced by a linear function in loop's index variables. The transformation, which does so, is called induction variable substitution. Since the variable K in Figure 1 is one induction variable, it can be replaced $z \times ((I_1 - L_1) \times (\prod_{p_1=2}^d (U_{p_1} - L_{p_1} + 1)) + (I_2 - L_2) \times (\prod_{p_2=3}^d (U_{p_2} - L_{p_2} + 1) + \dots + (i_d - L_d + 1))$ where d is the number of common loops and z is one integer variable (Banerjee, 1988, 1993, 1997; Paek, 1997; Hoeflinger, 1998). Therefore, the code in Figure 1 is transformed into the code in Figure 2, after finishing the processing of induction variable substitution for the variable K.

$$\begin{split} K &= 0 \\ FOR \quad I_1 &= L_1 \quad \text{TO} \quad U_1 \\ & \vdots \\ FOR \quad I_d &= L_d \quad \text{TO} \quad U_d \\ & \cdots \\ S_1 &: A(z \times ((I_1 - L_1) \times (\prod_{P_1 = 2}^d (U_{P_1} - L_{P_1} + 1)) + (I_2 - L_2) \times (\prod_{P_2 = 3}^d (U_{P_2} - L_{P_2} + 1)) \\ & + \cdots + (I_d - L_d + 1)) + C) = \cdots \\ S_2 &: \qquad \cdots &= A(z \times ((I_1 - L_1) \times (\prod_{P_1 = 2}^d (U_{P_1} - L_{P_1} + 1)) + (I_2 - L_2)) \\ & \qquad \times (\prod_{P_2 = 3}^d (U_{P_2} - L_{P_2} + 1)) + \cdots + (I_d - L_d + 1)) + C) \cdots \\ & \vdots \\ ENDFOR \\ &\vdots \\ ENDFOR \\ &\vdots \end{split}$$

Figure 2 The transformed loop after induction variable substitution for the induction variable K

Because dependence between S_1 and S_2 in Figure 2 may arise in different iterations of the common loops, we deal with the loop iteration variables referenced in S_1 as being different variables from those referenced in S_2 subject to common loop bounds. Therefore, when analysing dependence arising from a statement pair nested in d common loops, the problem will involve n unique variable

(where n = 2d). Furthermore, variables X_{2k-1} and X_{2k} ($1 \le k \le d$) are different instances of the same loop iteration variable, I_k . Assume that L_{2k-1} , L_{2k} , U_{2k-1} and U_{2k} are, respectively, lower bounds and upper bounds for X_{2k-1} and X_{2k} . Because variables X_{2k-1} and X_{2k} ($1 \le k \le d$) are different instances of the same loop iteration variable, I_k , lower bounds for X_{2k-1} and X_{2k} are the same and upper bounds for X_{2k-1} and X_{2k} also are the same.

The problem of determining whether there exists dependence for the array A between S_1 and S_2 in Figure 2 can be reduced to that of checking whether one system of a linear equation with n unknown variables has a simultaneous integer solution, which satisfies the constraints for each variable in the system. It is assumed that one linear equation in a system is written as:

$$z \times ((X_{1} - X_{2}) \times ((U_{2} - L_{2} + 1) \times \dots \times (U_{d} - L_{d} + 1))$$

$$+ (X_{3} - X_{4}) \times ((U_{3} - L_{3} + 1) \times \dots \times (U_{d} - L_{d} + 1))$$

$$+ \dots + (X_{2j-1} - X_{2j}) \times ((U_{j+1} - L_{j+1} + 1) \times \dots$$

$$\times (U_{d} - L_{d} + 1)) + \dots + (X_{2d-3} - X_{2d-2})$$

$$\times (U_{d} - L_{d} + 1) + (X_{2d-1} - X_{2d})) = 0,$$

$$(1)$$

where each L_k and each U_k are an integer variable and are, respectively, one lower bound and one upper bound for the k-the loop for $(1 \le k \le d)$. Because z is the greatest common divisor for all the coefficients in the left-hand side of equation (1), all the coefficients in equation (1) are divided by z and equation (1) is rewritten as

$$\begin{split} &(X_1-X_2)\times((U_2-L_2+1)\times\cdots\times(U_d-L_d+1))\\ &+(X_3-X_4)\times((U_3-L_3+1)\times\cdots\times(U_d-L_d+1))\\ &+\cdots+(X_{2j-1}-X_{2j})\times((U_{j+1}-L_{j+1}+1)\times\cdots\times(U_d-L_d+1))\\ &+\cdots+(X_{2d-3}-X_{2d-2})\times(U_d-L_d+1)+(X_{2d-1}-X_{2d})=0. \end{split}$$

It is postulated that the constraints to each variable in equation (2) are represented as

$$L_{k} \le X_{2k-1} \text{ and } X_{2k} \le U_{k}, \tag{3}$$

where $(1 \le k \le d)$. Let us use an example to make clear the illustrations stated above. Consider the nested do-loop in Figure 3. The variable K in Figure 3(a) is incremented by *one* in each iteration in the nested loop. So it is a one induction variable. After finishing the processing of induction variable substitution for the induction variable K, the result is shown in Figure 3(b). In Figure 3(b), the lower and upper bounds of the first (outer) loop and the second (inner) loop are, respectively, 1 and 10. Therefore, the bounds of the do-loop are constants. This do-loop executes 100 iterations by consecutively assigning the values 1, 2, ..., 10 to J and I and executing the body (the main statement S) exactly once in each iteration. The net effect of the do-loop execution is then the ordered execution of the statements:

the Interval Test (the I test and the direction vector I test) to be applied for resolving the problem stated above. Also, it is proved from the proposed theoretical aspects that under a specific direction vector $\vec{\theta} = (=_1, ..., =_d)$ there are integer-valued solutions for one-dimensional arrays with subscripts formed by induction variable and under other specific direction vectors there are no integer-valued solutions. Experiments with benchmarks, cited from Parallel loop, Vector loop and TRFD (Perfect benchmark), reveal that this framework can properly enhance the precision of data dependence analysis for one-dimensional arrays with subscripts mentioned above. The proposed theorems can improve the precision of data dependence analysis for one-dimensional arrays with references formed by induction variable. Depending on the application domains, it is suggested that the proposed theorems be applied together with the front-end of a parallelising compiler to provide data dependence analysis for one-dimensional arrays with references formed by induction variable.

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